# ZLAN6042/6002 Remote IO Controller User Manual

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	<b>D</b>		Add 6042 control test and usage of
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# 1. Summary

ZLAN6042, ZLAN6002, ZLAN6032 Remote IO Controller is an intelligent device developed by Shanghai ZLAN of digital input output and analog quantity input based on Ethernet or RS485. The remote IO controller can conveniently connect to Ethernet and 485 bus to realize accessing TCP connection, RS485 and webpage. ZLAN6042, ZLAN6002, ZLAN6032 are the ideal choices for user realizing remote control and data acquisition.

**ZLAN6042:** Based on Ethernet transmission, support Modbus TCP to Modbus RTU, support virtual serial port, can monitor 4 channels digital input, 2 channels analog quantity input and control 4 channels relay output at the same time. The remote IO control and data acquisition use Modbus TCP protocol or Modbus RTU protocol.

**ZLAN6002:** Base on RS485 transmission, also can monitor 4 channels digital input, 2 channels analog quantity input and control 4 channels relay output at the same time. The remote IO control and data acquisition use Modbus protocol.



#### Figure 1 ZLAN6042

It can be applied to:

- building/e-guard system/security system;
- industry automation system;
- Intelligent home.

The typical application is showed in Figure 2. User connects IO devices to ZLAN6042 and connects ZLAN6042 to Ethernet. Then the PC software can control the IO devices by Modbus TCP or Modbus RTU through virtual serial port.



Figure 2 connecting example

# 2. Feature

1) 4 Digital input:

- Passive switch (dry node)
- Active power level (wet node, low level voltage is 0~3V; high level voltage is 8~24V, measuring in 24V power)
- 2) 2 Analog quantity input: different input method corresponding to different sub-models.
  - Voltage signal input: 0~5V or 0~10V.
  - Current signal input: 4~20mA.
  - Resistant input: 0~10k or resistant type temperature/ humidity sensor and so on.
- 3) 4 digital output.

Relay output (5A@AC250V/DC 30V)

- ZLAN6042 is equipped freely with our Windows Virtual Serial & Device Management Tool ZLVirCom. It supports virtual serial and searching device or modifying parameters with ZLVircom.
- Provide device management library (Window DLL library). It will help user to develop program with VC, VB, Delphi, C++ Builder. User need only use read or write function to communicate with ZLAN6042.
- 6) ZLAN6042 support DHCP, solve IP management and IP conflict problem.
- 7) ZLAN6042 support DNS, can realize communication through domain name.
- 8) ZLAN6042 support 100 TCP connections communicate with network module.
- 9) ZLAN6042 has high cost performance.
- 10) ZLAN6042 2KV ESD Ethernet port protection.

# 3. Technical Parameters

Figure	
Size:	L x W x H =12.2cm×7.2cm×3.4cm

Serial Port (ZLAN600	)2 only)
RS485 port, 1200~11	5200bps(default 9600),8bits、NONE parity、1stop bit
Software	
App protocol	Modbus RTU / Modbus TCP
Physical protocol	Ethernet, RS485
Relay Transmission	Time( Response time)
ZLAN6042/ ZLAN6002	2: <30ms
Al Input Format	
Current: 4~20mA,0~2	0mA
Votage: 0~5V, 0~10V	/
Resister: 0~10K, temp	perature/humidity sensor
Power Consumption	
ZLAN6042/ ZLAN603:	2: <1.8W <75mA @24V
ZLAN6002: <1.7W	<70mA@24V
Environment	
Operation temp.	-40~85℃
Storage temp.	-45~165℃
Humidity:	5~95% relative

# 4. Hardware

ZLAN6042/ZLAN6002 front view are as Figure 1 and Figure 3. ZLAN6042/ZLAN6002 have slide rail slot on the bottom. It can be mounted on slide rail easily.

#### Panel led:

1) **ACT:** When this light is blue, it indicates data is transmitted between Ethernet and ZLAN6042.

2) LINK: When this light is green, it indicates the RJ45 line is plugged in. When this

light is blue, it indicates the TCP connection is established.

3) **POWER:** When this light is on, power is supplied.



Figure 3 Panel Light

ZLAN6042/ZLAN6002 the side interfaces are defined as:

Terminal	Function
1	GND
2	Power in 24VDC
3	No. 4 relay pin 1
4	No. 4 relay pin 2

5	No. 3 relay pin 1
6	No. 3 relay pin 1
7	No. 2 relay pin 1
8	No. 2 relay pin 2
9	No. 1 relay pin 1
10	No. 1 relay pin 2

ZLAN6042/ ZLAN6002 the other side interfaces are:

Interfaces	Function
RJ45	Ethernet or RS485
1	AI 2.
2	AI 1.
3	The common ground of AI or DI
4	DI 4
5	DI 3
6	DI 2
7	DI 1

#### Note:

- 1) If the type is ZLAN6002, The RJ45 is RS485 input, and 485A and 485B corresponding to RJ45 pin 1 and pin 2.
- There have the following sub-models of different AI input format. The default 2) sub-model is "-V5".
  - ZLAN6042-V5, ZLAN6002-V5: Voltage input 0~5V. The maximum value of the •

collection when reporting is 1024. So the real voltage is Al/1024 \* 5.

- ZLAN6042-V10, ZLAN6002-V10: Voltage input 0~10V. The maximum value of the collection when reporting is 1024. So the real voltage is Al/1024 \* 10.
- ZLAN6042-I20, ZLAN6002-I20: Current input 0~20mA. The report shows the resistance value, converted to the current formula: AI/1024 \* 25mA.
- ZLAN6042-R10K, ZLAN6002-R10K: resistance input 0~10K, the maximum is 10K.

## 5. Software/Protocol

ZLAN6042/ZLAN6002 is designed based on Modbus TCP and Modbus RTU, the command and register defined as follow:

Register Address	No. of DI/DO/AI	Modbus Command	Description	R/W
00001	0	01	No. 1 DI	Read Only
00002	1	01	No. 2 DI	Read Only
00003	2	01	No. 3 DI	Read Only
00004	3	01	No. 4 DI	Read Only
00017	0	01/05	No. 1 DO	Read/Write
00018	1	01/05	No. 2 DO	Read/Write
00019	2	01/05	No. 3 DO	Read/Write
00020	3	01/05	No. 4 DO	Read/Write
30001	0	04	No. 1 Al	Read Only
30002	1	04	No. 2 Al	Read Only

ZLAN6042/ZLAN6002 use MODBUS TCP or RTU to communicate with PC software.

These Modbus command is: read single coil group instruction, force setting single coil instruction, read input register instruction.

#### 1) Read single coil group instruction 0x01

bytes	1	1	1	1	1	1	1	1
name	address	command	Register addr high	Register addr low	Data Ien high	Data len low	CRC high	CRC low

For example: sending-> 01 01 00 00 00 04 3d c9

Return -> 01 01 01 0f 11 8c

#### 2) Read input register instruction 0x04

bytes	1	1	1	1	1	1	1	1
name	address	command	Register addr high	Register addr low	Data len high	Data len low	CRC high	CRC low

For example: sending -> 01 04 00 00 00 02 71 cb

Return -> 01 04 04 00 01 00 02 2b 85

#### 3) Force setting single coil instruction 0x05

bytes	1	1	1	1	1	1	1	1
name	address	command	Register addr high	Register addr low	Data len high	Data Ien Iow	CRC high	CRC low

For example: sending -> 01 05 00 10 ff 00 8d ff

Return -> 01 05 00 10 ff 00 8d ff

# 6. Function test

## 1) Test software function

RemoteIO software is a software tool for testing and configuring 6002/6042, as FIG

Name IP Port Work Mode Protocol Us  A Mode Pro	art Pa
Connect     Search       6002 Communication     6042/6002 param       Com:     COM1       Address:     1	4
Connect     Search       6002 Communication     6042/6002 param       Com:     COM1	•
Connect     Search       6002 Communication     6042/6002 param       Com:     COM1       Address:     1	
6002 Communication 6042/6002 param Address: 1	
Baudrate: 1200 - Advanced	
RL1 Closed RL2 Closed RL3 Closed RL4 Closed guery DI gu	ery AI
RL1 Disconnect RL2 Disconnect RL3 Disconnect RL4 Disconnect	
Realty state	
	J



Software has 5 parts, the first part is communication set of 6042 remote IO controller, the second is communication set of 6002 remote IO controller, the third part is 6042/6002 control part, the forth part is parameter set, the fifth part is report area.

## 2) Ethernet remote IO 6042

First connect 6042 to LAN via cable, then click "search" button so can search the 6042 devices in LAN, as FIG 5.

and the local sector of th		1		,	
Name	IP	Port Work	Mode	Protocol	Uart Par
					•
Connect	Search		5042/6002 param-		
Com: CC Baudrate: 12	M1 -		Address: 1		
Open S	ear ch		Advanced		
ontrol		871,372			_ AI
RL1 Closed	RL2 Closed	RL3 Closed	RL4 Closed	query DI	query AI
L1 Disconnect	RL2 Disconnect	RL3 Disconnec	t RL4 Disconnce		
					ALI
lealy state —	E RL2	┌─ RL3	T RL4	🗌 🗖 DI3 🦵 DI4	AI2 0
lealy state —	1107 - 1107 - 121				

#### **Figure 5 search**

You can see some devices in the showing list, the "ZLDEV0001" is 6042, after is IP, Port., Work Mode, Protocol, Uart Parameter. The work mode must be Server Mode, Protocol (Modbus RTU or Modbus TCP) should be same as the one on top right corner., if not same need use ZLVircom to configure. Serial parameter is 115200, 8, N, 1, or else there will be error prompt. The correct configuration is shown as FIG. 6.

Name IP ZLDEV0001 19	2 168 1 200	Fort Wo	rk Mode	frotocol	I HARACK DATE
	2. 100. 1. 200	4196 TC	P Server	MODBUS TCP	Correct
•			m.		•
Connect Se	arch				
5002 Communicatio	n	1	-6042/6002 param-		
Com: COM1	<u> </u>		Address: 1		
Baudrate: 1200	*				
	. 1		Advanced 1		
UpenSearc	n.		Advanced		
Control					AI
RL1 Closed	RL2 Closed	RL3 Close	d RL4 Closed	query DI	query AT
	o. p:	DIO D'	I DI 4 D		
LI DISCONNECT N	2 Disconnect	ALS Disconn	ect ML4 Discource.		AT1 0
· · · · · · · · · · · · · · · · · · ·					
Gealy state			A STATE OF A		AT2 0
Kealy state	T RL2	T RL3	B I RL4	DI3 DI4	U State

#### **Figure 6 Correct Configuration**

The IP and Port will be automatically filled after choosing the 6042 device. Click "connect" button will do TCP connection.

The information "TCP Client Connected to" on report area means TCP successfully made. Then the software will automatically detect device address and make "advanced" usable. Next you can test 6042 through buttons in control area.

## 3) 6002 RS485 Control

Connect RS485 wire to 485 port of 6002, open related port No. on RemoteIO, no need to choose baud rate, then click "search", wait the software searching devices. If searched one device there will be "already searched the device" on report area, otherwise shown as FIG. 7 "found no device".

	1.1.2.52 1.01	t.  4150	froto	COL	MODBO2 ICF	<u> </u>	
Name	IP	Port	Work Mode		Protocol		Uart Pa
∢		-	III				۱.
Connect	Search	Remo	oteEN 📃	×			
3002 Communic Com: C Baudrate: 1 Close S Control RL1 Closed	ation OM4 200 Search RL2 Closed	Fou	und no device! 确定	LOSEQ	DI query DI	1	AI query AI
L1 Disconnec	t RL2 Disconned	t RL3 Disc	connect RL4 Disc	conncet		DI2	AI1 0
Realy state —	🗖 RL2	Γ	RL3	RL4		DI4	AI2 0
Report — —							

#### Figure 7 No searched device

You can do simple test in control area to verify the hardware working well.

## 4) Advanced parameter

6002 and 6042 share a dialog box, do not use both models at the same time.

Click the "advanced", shown as FIG. 8.

Verrien	Ind	01
	1	Cancle
Siave Addr.	[*	
Baudrate	9600 -	
Enable DI initiative upload:	1	(O:Disable, 1:Enable)
DI upload address:	2	
AI1 initiative upload:	0	(0~65535m (0 means disable)
AI2 initiative upload:	0	(0~65535m (0 means disable)

Figure 8 Advanced Parameter

Firmware version: the version of the inside 6002 firmware.

Device address: 6002 device slave-station address (Modbus addr.)

Baud rate: 6042

Report address: please refer to next section

Modify the corresponding parameters, click the "Settings" button to complete the changes. Need to restart the device to make it effective.

# 7. DI Active Reporting

6042 is standard Modbus device, use question and answer form. Some users want active return function, here we introduce the active reporting function of 6042.

As FIG. 9, set "Enable DI initiative upload" to 1, the function open. The reporting address can be set at 0~255, it will be filled to the address field in the feedback instruction. If want original type, set to 0.

	land.	07
Version:	IAPI	
Slave Addr:	1	Lancie
Baudrate	9600 💌	
Enable DI initiative upload:	1	(O:Disable, 1:Enable)
DI upload address:	2	•
AI1 initiative upload:	0	(0~65535m (0 means disable)
AI2 initiative upload:	0	(0~65535m (0 means disable)



# 8. Al Active Reporting

The AI active reporting function is to make the collected analog value automatically send to host, no need the host to do Modbus instruction query.

It can set reporting time of A1 and A2. Time interval can be selected 2~65535ms. If set to 0 means not open this function. The "Advanced" as FIG 10, the RemoteIO software version must above 2014.12.22, the firmware version must be above V5.

Version:	Уъ	OK
Slave Addr:	1	Cancle
Baudrate	9600 -	•
Enable DI initiative upload:	0	(O:Disable, 1:Enable)
DI upload address:	0	
AI1 initiative upload:	1000	(0~65535m (O means disable)
AI2 initiative upload:	0	



Here set reporting time of AI1 & AI2. The resolution of reporting time is 200ms. (1~200ms,

200ms report once; 201~400ms, 400ms report once; and so on)

The data format is same for reporting and returned of Modbus query.

#### 1) If only A1 or A2 be set, the reporting instruction:

- a. No conversion protocol instruction: aa 04 02 xx yy c1 c2
- b. Conversion protocol is Modbus TCP to RTU instruction: s1 s2 00 00 00 05 aa 04
   02 xx yy

aa means device addr., xx yy is reporting AI value, the hexadecimal means voltage value, c1 c2 IS CRS check. S1 s2 is ordinal number of Modbus TCP, generally not handle.

The A1 and A2 upload instructions are the same, so the user should know if it is A1 or A2, because only one in A1 and A2 is allowed to upload. Note that when only A2 is selected, the number of active reporting is shown in the box of the collection of A1 in the RemotelO program.

#### 2) If A1 and A2 both be set, the reporting instruction:

- a. No conversion protocol instruction: aa 04 04 x1 y1 x2 y2 c1 c2
- b. Conversion protocol is Modbus TCP to RTU instruction: s1 s2 00 00 00 07 aa 04
   04 x1 y1 x2 y2

Here x1 y1 represents the acquisition of A1, x2 y2 represents the acquisition of A2. A1 and A2 are set at the same time, the reporting period is mainly the small period, and the quantity of A1 and A2 is reported simultaneously in the packet.

## 9. Two used in pairs

Considering the user needs to control the DO output through DI input, however, DI input devices and the DO output devices are far apart, so we can connect two 6042 through the Ethernet network, to realize DI remote control the DO output. DI inputs only control the corresponding DO. For example, DI1 of device 1 control DO1 1 of device 2, DI2 of device 1 control DO2 of device 2, and so on.



DevA: Client DestIP: 192.168.1.201 DestPort: 502 Slaveaddress:1

DevB:Server IP: 192.168.1.201 Port: 502 Slaveaddress:2

#### Figure 11 6042 Pairs-connection Control

As shown in FIG. 11 6042, two 6042 are connected by Ethernet.

First set the two 6042, as shown in figure 14 DevA, here need reporting addr., whether to submit. According to the functional test content in the previous chapter, search and connect device DevA, enter the "advanced", device address is set to 1, " Enable DI initiative upload " fill in the 1 means open this feature, "DI upload address" is the need to control the remote device address of 6042, it set to 2. DevA setup.

Version:	VD	OK
Slave Addr:	1	Cancle
Baudrate	9600 👻	]
Enable DI initiative upload:	1	(O:Disable, 1:Enable)
DI upload address:	2	-
AI1 initiative upload:	0	(0~65535m (O means disable)
AI2 initiative upload:	0	

Figure 12 DevA configuration

Then, search and connect the device DevB, enter the advanced parameter, set the device address to 2, whether to submit is set to 1, and the report address is 1 (DevA). Following this setting, when DevA's DI changes, a control DO instruction is sent to DevB. Similarly, the DI change of DevB also sends a control instruction to DevA.

Advanced	
Version:	Vb
Slave Addr:	2 Cancle
Baudrate	9600 💌
Enable DI initiative upload:	1 (O:Disable, 1:Enable)
DI upload address:	1
AI1 initiative upload:	0 (0~65535m (0 means disable)
AI2 initiative upload:	0 (0~65535m (0 means disable)

#### Figure 13 DevB configuration

Configure the DevA and DevB parameters to establish the TCP connection. DevB works in server mode, sets work IP and port, DevA as client mode, sets up DevA's destination IP and port as DevB's IP and port. For specific Settings, please refer to the <guide to the use of ZLAN networking products>.

## 10. How to use

## 1) How to use ZLAN6042

Here we introduce how to use ZLAN6042 by using the software named modbus poll.

There are 2 methods to communicate with 6042: virtual serial port and Modbus TCP. When use Modbus TCP, the modbus poll act as Modbus master and query register of 6042. Note user must set APP protocol of 6042 to "Modbus TCP to RTU" for this method. When use the seconde method, Modbus poll open a virtual serial port(eg. COM5) created by zlvircom.exe. And communicate use Modbus RTU. For more information of parameter config of 6042 or virtual serial port please refer to <User manual of net link product>.

Open modbus poll software as FIG 14:

🔁 🖬 bpoll	l.						
Tx = 0: E	rr = 0: I	D = 1: 1	F = 03:	SR =	1000m	ຣ	
No Connec	tion						
40001 =	0						
40002 =	0						
40003 =	0						
10004 =	0						
40005 =	0						
40006 =	0						
40007 =	0						
40008 =	0						
40009 =	0						
40010 =	0						
10010 -							
10010 -							

## Figure 14

Then press SETUP, and config a new polling name POLL1 to read DI as Figure 15:

Slave	1	OK
Function:	01 Read Coils	Cancel
Address: Length:	4	Apply
Scan Rate:	500 ms	
Enshle	Polling	Poll Once

Figure 15

Then config a new POLL2 to read DO as Figure 16:

Function: 01 Read Coils Ca Address: 17	n cel
Address: 17	TICET
Length: 4	ply
Scan Rate: 500 ms	

Figure 16

Then config a new POLL3 to read AI as Figuere 17:

Poll Def	inition	×
Slave	1	OK
Function:	04 Read Input Registers 💌	Cancel
Length:	2	Apply
Scan Rate:	500 ms	
🔽 Enable	Polling	Poll Once

Figure 17

After all that config, then see following as Figure 18:

웹 Todbus Poll - Thpoll3	
File Connection Setup Functions Display View Window Help	
🗋 🗅 🚅 🖬 🎒 🗙 🗂 🗒 🚊 🎵 05 06 15 16 22 23 101 💡 🕅	
💬 Ibpolli	
Tx = 0: Err = 0: ID = 1: F = 01: SR = 500ms No Connection 00001 = 0 00002 = 0 00003 = 0 00004 = 0	
📴 Ibpoll2	
Tx = 0: Err = 0: ID = 1: F = 01: SR = 500ms No Connection 00017 = 0 00018 = 0 00019 = 0 00020 = 0	
👺 Mbpoll3	
Tx = 0: Err = 0: ID = 1: F = 04: SR = 500ms No Connection 30001 = 0 30002 = 0	
For Help, press F1. For Edit, double click on a value.	Port 6: 57600-8-N-1

Figure 18

Following we show how to use virtual serial port method., Config connection as Figure

19. Then press OK to open the COM6 to communicate with  $6042_{\,\circ}$ 

Connection		×
Port 6 💌	Mode © RTU C ASCII	ОК
115200 Baud 💌	Response Timeout	Cancel
8 Data bits 💌	1000 [ms]	
None Parity 💌	Delay Between Polls	
1 Stop Bit 💌	5 [ms]	Advanced
Remote Server IP Address	Port	
192.168.1.150	502	

Figure 19

Following we show the Modbus TCP method. Config connection as Figure 20, press OK to start tcp connection with 6042.

Cancel
lls
Advanced
2787787

Figure 20

## 2) How to use ZLAN6002

The method to use ZLAN6002 is much familiar to virtual serial port method of ZLAN6042. The only difference is when in 6002 the serial port is real serial port, and in 6042 the serial port is virtual serial port. You may need a RS232 to RS485 convertor to connect between you PC real serial port and 6002 RS485 port.

Note that RJ45 is modified for RS485 connection. Also RJ45 can also be changed to RS232, RS422 wiring. RJ45 cable line sequence and serial line sequence correspondence table is as follows:

Interface Type of	Cable pin1	Cable pin2	Cable pin3	Cable pin6
RJ45				
RS485	А	В	NC	NC
RS232	NC	RXD	TXD	GND
RS422	485A	485B	422A	422B

For the convenience of users ZLAN provides a standard Ethernet port to RS232 cable and Ethernet port to 485 cable. Note the following:

- If it is ZLAN6002-232: can be equipped with standard ZLAN " Ethernet port to RS232 cable", pay attention that whether ZLAN has short circuit the cable pin5,6.
- If it is ZLAN6002-485: can be equipped with ZLAN "Ethernet port to 485 cable" + DB9\_485\_232 adapter board. And the DB9\_485\_232 adapter board DB9 pin 8 and 9 shorted. After that DB9\_485\_232 adapter board 1 terminal is 485B, 2 terminal is 485A.

# 11. Support

Shanghai ZLAN information Co., Ltd.

Address: 12 floor, D building, No. 80 CaoBao road, Xuhui District, Shanghai, China

Phone: 021-64325189

Fax: 021-64325200

Web: http://www.zlmcu.com

Email: support@zlmcu.com